

# AN ON-LINE ALGORITHM FOR REORIENTATION OF GRAPHS

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There exists an on-line algorithm which takes as

**INPUT** a pseudo-transitive oriented graphs  $(V, \rightarrow)$  (possibly infinite)

and gives as

**OUTPUT** a transitive oriented graph  $(V, \prec)$  such that  $a \rightarrow b \Leftrightarrow a \prec b$

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**INPUT** a **pseudo-transitive** oriented graphs  $(V, \rightarrow)$  (possibly infinite)

For each  $a, b, c \in V$   
if  $a \rightarrow b \rightarrow c$  then  
 $a \rightarrow c$  or  $c \rightarrow a$ .

and gives as

**OUTPUT** a transitive oriented graph  $(V, \prec)$  such that  $a \rightarrow b \Leftrightarrow a \prec b$

Let  $(\{v_n \mid n \in \mathbb{N}\}, \rightarrow)$  be a pseudo-transitive oriented graph

## INPUT

at stage  $n$  the algorithm reads

- the  $n^{\text{th}}$  vertex  $v_{n-1}$  of  $(V, \rightarrow)$ ,
- the edges connecting  $v_n$  to  $\{v_0, \dots, v_{n-1}\}$

At most  $n$  new bits  
of information at  
each step

## OUTPUT

at stage  $n$  the algorithm outputs

- a transitive reorientation of all the edges connecting  $v_n$  to  $\{v_0, \dots, v_{n-1}\}$ ,
- preserves the reorientations already set at previous stages

No mind changes

## **Theorem (Ghouila-Houri)**

For each pseudo-transitive oriented graph there exists a transitive reorientation.

Ghouila-Houri's proof gives a non on-line algorithm to reorient finite oriented graphs.

Our improvements:

- we give an algorithm for infinite oriented graphs
- every computable pseudo-transitive oriented graph has a computable transitive reorientation.
- we prove that there exists an on-line algorithm for the finite case

## **Theorem (Hirst)**

The following statement is NOT computably true:

If an undirected graph is such that every cycle of odd length has a triangular chord, then it is transitively orientable.

## **Corollary**

There is no on-line algorithm to transitively orient an undirected graph such that every cycle of odd length has a triangular chord.

There exists an on-line algorithm which takes as

**INPUT** a pseudo-transitive oriented graphs  $(V, \rightarrow)$  (possibly infinite)

and gives as

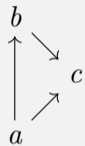
**OUTPUT** a transitive oriented graph  $(V, \prec)$  such that  $a \mid_{\rightarrow} b \Leftrightarrow a \mid_{\prec} b$

# Obstacles: transitive triangle

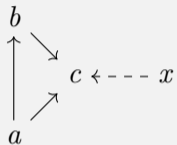




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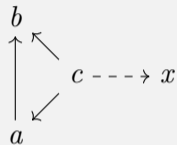
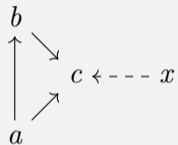
# Obstacles: transitive triangle



$a \prec c \prec b$  is NOT extendible

$(V, \rightarrow, \prec)$  is extendible if for every  $(V \cup \{x\}, \rightarrow')$ , pseudo-transitive extension of  $(V, \rightarrow)$ , there exists  $\prec' \supseteq \prec$  transitive reorientation of  $(V \cup \{x\}, \rightarrow')$

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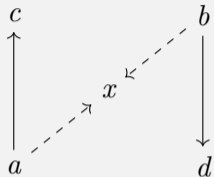
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# Obstacles: $2 \oplus 2$ example

$c$   
↑  
 $a$

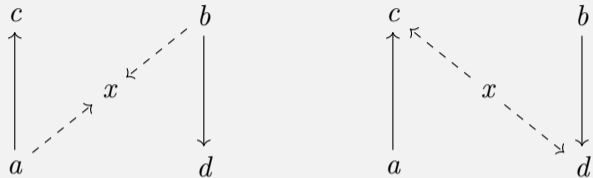
$b$   
↓  
 $d$

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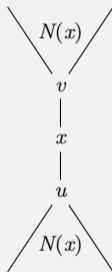
Let  $(V, \rightarrow)$  be a pseudo-transitive graph and  $\prec$  a transitive reorientation.

If  $(V \cup \{x\}, \rightarrow')$  is a pseudo-transitive extension of  $(V, \rightarrow)$  let

$$N(x) = \{a \in V \mid a \rightarrow' x \vee x \rightarrow' a\}$$

$$N^+(x) = \{v \in N(x) \mid \forall w (v \prec w \Rightarrow w \in N(x))\};$$

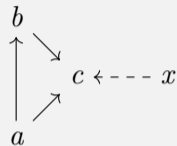
$$N^-(x) = \{u \in N(x) \mid \forall w (w \prec u \Rightarrow w \in N(x))\}.$$



# Back to transitive triangles

Let  $(V, \rightarrow)$  be a pseudo-transitive graph and  $\prec$  a transitive reorientation.

- For any  $(V \cup \{x\}, \rightarrow')$  pseudo-transitive extension of  $(V, \rightarrow)$  the following are equivalent:
  - $N(x) = N^+(x) \cup N^-(x)$ ;
  - $\forall a, b, c \in V (a \prec c \prec b \wedge x -' c \Rightarrow x -' a \vee x -' b)$ .





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(i)  $N(x) = N^+(x) \cup N^-(x)$ ;

(ii)  $\forall a, b, c \in V (a \prec c \prec b \wedge x -' c \Rightarrow x -' a \vee x -' b)$ .

- $\Phi$  and  $\Psi$  are satisfied

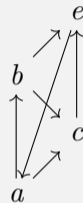
$\varphi(a, b, c) :=$  there exists  $e_0, \dots, e_n \in V$  such that:

( $\varphi_1$ )  $c \rightarrow e_0$ ;

( $\varphi_2$ )  $\forall i < n ((a \rightarrow e_i \wedge b \rightarrow e_i \rightarrow e_{i+1}) \vee (e_{i+1} \rightarrow e_i \rightarrow b \wedge e_i \rightarrow a))$ ;

( $\varphi_3$ )  $a \rightarrow e_n \rightarrow b \vee b \rightarrow e_n \rightarrow a$ .

Then  $\Phi$  is  $\forall a, b, c \in V (a \rightarrow c \leftarrow b \wedge a \prec c \prec b \Rightarrow \varphi(a, b, c))$

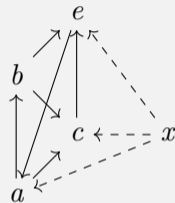


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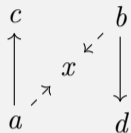
## Back to $2 \oplus 2$

Let  $(V, \rightarrow)$  be a pseudo-transitive graph and  $\prec$  a transitive reorientation which satisfy  $\Phi$  and  $\Psi$ .

- For any  $(V \cup \{x\}, \rightarrow')$  pseudo-transitive extension of  $(V, \rightarrow)$  the following are equivalent:

(i)  $N^-(x) \setminus N^+(x) \prec N^+(x) \setminus N^-(x)$ ;

(ii)  $\forall a, b, c, d \in V (a \mid b \wedge c \mid d \wedge a \prec c \wedge d \prec b \wedge x -' a \wedge x -' b \Rightarrow x -' d \vee x -' c)$ .



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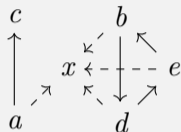
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- $\Theta$  is satisfied



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- $\Theta$  is satisfied

$\theta(a, b, c, d) :=$  there exists  $e_0, \dots, e_n \in V$  such that:

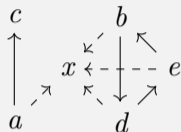
$(\theta_1)$   $e_0 \rightarrow b$ ;

$(\theta_2)$   $\forall i < n (e_{i+1} \rightarrow e_i \rightarrow d)$ ;

$(\theta_3)$   $d \rightarrow e_n$ ;

$(\theta_4)$   $e_n \mid a$ .

Then  $\Theta$  is  $\forall a, b, c, d \in V (a \rightarrow c \wedge b \rightarrow d \wedge a \mid b \wedge c \mid d \wedge a \prec c \wedge d \prec b \Rightarrow \theta(a, b, c, d) \vee \theta(b, a, d, c))$



# Algorithm

Let  $(V, \rightarrow)$  be a pseudo-transitive oriented graph and  $\prec$  a reorientation.  
If  $(V \cup \{x\}, \rightarrow')$  is a pseudo-transitive extension of  $\rightarrow$ , we define inductively the following subsets of  $N(x)$ :

$$S_0^-(x) = N^-(x) \setminus N^+(x);$$

$$S_0^+(x) = N^+(x) \setminus N^-(x);$$

$$S_i(x) = S_i^-(x) \cup S_i^+(x);$$

$$S_{i+1}^-(x) = \{a \in N(x) \setminus \bigcup_{j \leq i} S_j(x) \mid \exists s \in S_i^-(x)(a \mid s)\};$$

$$S_{i+1}^+(x) = \{a \in N(x) \setminus \bigcup_{j \leq i} S_j(x) \mid \exists s \in S_i^+(x)(a \mid s)\}.$$

Let  $S^+(x) = \bigcup_{i \in \mathbb{N}} S_i^+(x)$ ,  $S^-(x) = \bigcup_{i \in \mathbb{N}} S_i^-(x)$ .

Let  $T(x) = N(x) \setminus S(x)$ .

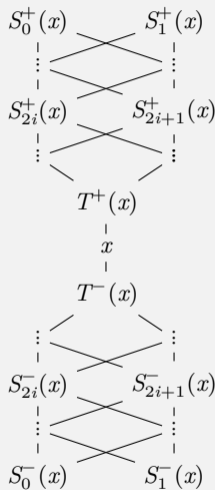
# Algorithm

**INPUT**  $(\{v_n \mid n \in \mathbb{N}\}, \rightarrow)$  pseudo-transitive oriented graph

**PARTIAL OUTPUT**  $(\{v_0, \dots, v_n\}, \prec)$  transitive reorientation

**A STEP**  $(\{v_0, \dots, v_n, x\}, \prec')$  such that for each  $i \leq n$

- if  $v_i \notin N(x)$  let  $v_i \not\prec' x$  and  $x \not\prec' v_i$ ,
- if  $v_i \in S^-(x)$  let  $v_i \prec' x$ ,
- if  $v_i \in S^+(x)$  let  $x \prec' v_i$ ,
- if  $v_i \in T(x)$  then
  - (a) if there exists  $j < i$  such that  $v_i \prec v_j \prec' x$  let  $v_i \prec' x$ ,
  - (b) if there exists  $j < i$  such that  $x \prec' v_j \prec v_i$  let  $x \prec' v_i$ ,
  - (c) otherwise let  $v_i \prec' x$  if  $v_i \rightarrow' x$   
and  $x \prec' v_i$  if  $x \rightarrow' v_i$ .



**A STEP**  $(\{v_0, \dots, v_n, x\}, \prec')$  such that for each  $i \leq n$

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We need to check that

- $\prec'$  is a reorientation
- $\prec'$  is transitive



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If  $S^-(x) \cap S^+(x) = \emptyset$  and  $S(x) \cap T(x) = \emptyset$ ,  
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If  $(V, \rightarrow), \prec$  satisfy  $\Phi, \Psi$  and  $\Theta$ ,  
then  $S^-(x) \cap S^+(x) = \emptyset$  and  $S(x) \cap T(x) = \emptyset$

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We need to check that

- $\Sigma, \Psi, \Theta$  are satisfied
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We need to check that

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**INPUT**  $(\{v_n \mid n \in \mathbb{N}\}, \rightarrow)$  pseudo-transitive oriented graph

**PARTIAL  
OUTPUT**  $(\{v_0, \dots, v_n\}, \prec)$  transitive reorientation

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OUTPUT**  $(\{v_0, \dots, v_n\}, \prec)$  transitive reorientation

$(\{v_0, \dots, v_n\}, \prec)$  transitive reorientation  $\Rightarrow$

$\prec$  satisfy  $\Phi, \Psi, \Theta \Rightarrow$

$(\{v_0, \dots, v_n, v_{n+1}\}, \prec')$  transitive reorientation

We need to check that

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**PARTIAL OUTPUT**  $(\{v_0, \dots, v_n\}, \prec)$  transitive reorientation

$(\{v_0, \dots, v_n\}, \prec)$  transitive reorientation  $\Rightarrow$

$\prec$  is **lazy**  $\Rightarrow$

$\prec$  satisfy  $\Phi, \Psi, \Theta \Rightarrow$

$(\{v_0, \dots, v_n, v_{n+1}\}, \prec')$  transitive reorientation

If  $v_i \rightarrow v_j$  and  $v_j \prec v_i$   
there exists  $v_h$  such that  
 $v_j \rightarrow v_h \rightarrow v_i$ ,  
 $v_j \prec v_h \prec v_i$ , and  
 $h < \min(i, j)$

# Complexity

The complexity of a step of the algorithm is  $O(|V|^2)$ .

- at most  $|V|^2$  steps to compute  $S_0^+(x)$  and  $S_0^-(x)$
- the remaining members of  $S^+(x)$  and  $S^-(x)$  can be found by a depth-first search algorithm applied to the non-adjacency graph  $(V \cup \{x\}, E')$  ( $O(|V| + |E|)$ )
- the rest is linear

The problem of orienting comparability graphs can be solved by an algorithm with complexity  $O(\delta \cdot |E|)$ , where  $\delta$  is the maximum degree of a vertex